

## **ABSTRACT**

A method for automatically scanning a side view mirror of a vehicle maintains an original state of the side view mirror during driving and sends a control signal via a turning-signal processing unit or a steering-wheel processing unit to determine which 5 side view mirror to scan. The selected side view mirror is driven to scan automatically in real time. A steering wheel or and a front tire is returned to a predetermined angle. The side view mirror returns to the original state thereof simultaneously.